A Study and Analysis of Image Compression by Wavelet Transform Technique: A Fuzzy Logic Approach

Dr. Harshad I. Gelada¹, Dr. Magan. P. Ghatule²
Department of Computer Science¹²
Sinhgad College of Science, Ambegaon (Bk), Pune-411041
geladaharshad@gmail.com, gmagan@rediffmail.com

Abstract: In the presence innovative studies development and analysis of image compression algorithm based on the wavelet transform method (I. Daubechies 1998) using Fuzzy Logic technique is implemented. At presence data storage and its transformation and transportation is a challenging task. And it can be overcome by digitalization processes. However digital imaging (Rafael C. Gonzalez) is one of the best data storage technique commonly used in real practice.

This article emphasizes on transportation or transition of imaged data so that it is essential that there will not be any change in shape, size and quality. To overcome this challenge various tools and techniques have been implemented and quality of assurance is achieved. In this sense image compression is one of the best benchmark techniques used for solving the said problem which comprises of wavelet transform comprises.

Form the literature review it is clear that present mathematical model used in the wavelet transformation has found some limitations and which scavenges considerable amount of error in the entire image process results. These results lead to decrease in the quality and efficiency of the processed image. Therefore in continuation with our earlier studies and to overcome this sensitive issue, an innovative mathematical model is embedded for enhancing the present algorithm which is based on Fuzzy Logic Technique (FLT).

In present research work appropriate Fuzzy Logic (FL) is used for enhancement in the analysis of image quality measures which is based on the Wavelet Transform Algorithm (WTA). The derived fuzzy Image Compression Model (FICM) deals with the vagueness uncertainties and controls the nonlinearities while processing the image compression. This algorithm ensures the design and development of FICM based on the fuzzy set theory and classical mathematical principles, in which approximate reasoning of Fuzzy Logic is implemented.

This summarizes implementation of human intelligence; knowledge and excellent wavelet transform technique to design fuzzy Image Compression Model (FICM).

This innovative research work describes how FICM is a powerful and alternative technique as compared with conventional algorithm of image compression. This research work comprises the suitability and flexibility of FICM, which directly deals with non-stationary and uncertain behavior of traditional image compression methods.

Index Terms – Images, Matlab, Fuzzy Model

1. INTRODUCTION

Digital Image compression (Rafael C. Gonzalez) addresses the problem of reducing the amount of data required to represent a digital image. The underlying basis of the reduction process is removal of redundant data. From the mathematical viewpoint, this amounts to transforming a 2D pixel array into a statically uncorrelated data set (Piella, 2014). The data redundancy is not an abstract concept but a mathematically quantifiable entity. If n1 and n2 denote the number of information-carrying units in two data sets that represent the same information, the relative data redundancy \( R_D \) [2] of the first data set (the one characterized by n1) can be defined as,

\[
R_D = 1 - \frac{1}{C_R} \tag{1}
\]

Where \( C_R \) called as compression ratio [2]. It is defined as

\[
C_R = \frac{n1}{n2} \tag{2}
\]

In image compression, three basic data redundancies can be identified and exploited:
(1) Coding redundancy,
(2) Interpixel redundancy, and
(3) Phychovisal redundancy.

Image compression is achieved when one or more of these redundancies are reduced or eliminated. The image compression is mainly used for image transmission and storage. There are number of image transmission
applications, which are in broadcast television, remote sensing via satellite, air-craft, radar, sonar; teleconferencing, computer communications, facsimile transmission etc. General Model of image compression is as shown in Figure (1.1)

![Image Compression Diagram](image)

**Figure (1.1) Block Diagram of Image Decompression**

However, image storage is required most commonly for educational and business documents, medical images like in computer tomography (CT), magnetic resonance imaging (MRI) and digital radiology, motion pictures, satellite images, weather maps, geological surveys, and many more. Generally there are two types of image compression techniques are used in real practice: (1) Lossy Image compression (2) Lossless Image compression (G. Piella, 2001)

### 2. WAVELET APPROACH FOR IMAGE COMPRESSION:

Storage constrains and bandwidth limitations in communication systems have necessitated the search for efficient image compression techniques. For real time video and multimedia applications where a reasonable approximation to the original signal can be tolerated, lossy compression is used (G. Piella, 2001). In the recent past, wavelet based image compression schemes have gained wide popularity. The characteristics of the wavelet transform provide compression results that outperform other transform techniques such as discrete cosine transform (DCT). Consequently, the JPEG2000 compression standard and FBI fingerprint compression system have adopted a wavelet approach to image compression.

The wavelet coding techniques is based on the idea that the co-efficient of a transform that decorrelates the pixels of an image can be coded more efficiently than the original pixels themselves. If the transform’s basis functions in this case wavelet- pack most of the important visual information into small number of co-efficient, the remaining co-efficient can be coarsely quantized or truncated to zero with little image distortion.

The still image compression(David Salomon’s), modern DWT based coders have outperformed DCT based coders providing higher compression ratio and more peak signal to noise ratio (PSNR) due to the wavelet transforms(H.J.A. M. Heijmans) multi-resolution and energy compaction properties and the ability to handle signals.

### 3. IMAGE COMPRESSION: WAVELET TRANSFORM TECHNIQUE (WTT)

We consider a \((K + 1)\) band Filter bank decomposition with inputs \(x, y(1), y(2), y(3)…y(K)\), with \(K \geq 1\), which represent the polyphase components of the analyzed signal. The first polyphase component, \(x\), is updated using the neighboring signal elements from the other polyphase components, thus yielding an approximation signal. Subsequently, the signal elements in the polyphase components \(y(1), y(2)…y(K)\) are predicted using the neighboring signal elements from the approximated polyphase component and the other polyphase components. The prediction steps, which are non-adaptive, result in detail coefficients. The adaptive update step is illustrated in Figure 3.1.

![Adaptive Update Lifting Scheme](image)

**Figure 3.1. Adaptive update lifting scheme**

Here, \(x\) and \(y(1), y(2)…y(K)\) are the input for a decision map \(D\), whose output at location \(n\) is binary decision

\[ d_n = D\{y(1), y(2)…y(K)\} \in \{0,1\} \]

Which triggers the update filter \(U_d\) and the addition \(\oplus\). More precisely, if \(d_n\) is the binary decision at location \(n\), then the updated value \(x^1(n)\) is given by

\[ x^1(n) = x(n) \oplus U_d y(n) \] \[ \quad \text{-------- (3.1)} \]

We assume that the addition \(\oplus\) is of the form \(x \oplus u = \alpha_d(x+u)\) with \(\alpha_d \neq 0\), so that the operation is invertible. The update filter is taken to be of the form

\[ U_d(y)(n) = \sum_{j=-L_1}^{L_2} \lambda_{d,j} y_j(n) \] \[ \quad \text{-------- (3.2)} \]

Where \(y_j(n) = y(n+j)\) and \(L_1\) and \(L_2\) are nonnegative integers. The filter coefficients \(\lambda_{d,j}\) depend on the decision \(d\) at location \(n\). Henceforth, we will use \(\Sigma_j\) to denote the summation from \(-L_1\) to \(L_2\).

From (3.1) and (3.2), we infer the update equation used at analysis:

\[ x^1(n) = \alpha_{d,n} x(n) + \sum_{j=-L_1}^{L_2} \beta_{d,n,j} y_j(n) \] \[ \quad \text{-------- (3.3)} \]

Where \(\beta_{d,j} = \alpha_d \lambda_{d,j}\). Clearly, we can easily invert (3.3) through...
\[ x(n) = \frac{1}{\alpha_{dn}} (x^1(n) - \sum_j \beta_{dn,j} y_j(n)) \quad (3.4) \]

Presumed that the decision \( d_n \) is known at every location \( n \). Thus, in order to have perfect reconstruction, it must be possible to recover the decision \( d_n = D(x, y)(n) \) from \( x^1 \) (rather than \( x \) which is not available at synthesis) and \( y \). This amounts to the problem of finding another decision map \( D^1 \) such that

\[ D(x, y_j)(n) = D^1(x^1, y_j)(n) \quad (3.5) \]

Where \( x^1 \) is given by (3.1). It can be shown that a necessary, but in no way sufficient, condition for perfect reconstruction is that the value

\[ \alpha_{dn} + \sum_j^N \beta_{dn,j} = 1. \]

### 3.3. COMBINING NORMS TECHNIQUE:

The input images \( x, y_1, y_2 \) and \( y_3 \) are obtained by a polyphase decomposition of an original image \( x_0 \) is given by,

\[
\begin{align*}
x(m, n) &= x_0(2m, 2n), \\
y_1(m, n) &= x_0(2m, 2n+1), \\
y_2(m, n) &= x_0(2m+1, 2n), \\
y_3(m, n) &= x_0(2m+1, 2n+1)
\end{align*}
\]

| \( x_0(m-1,n-1) \) | \( x_0(m-1,n) \) | \( x_0(m-1,n+1) \) |
| \( x_0(m-1,n) \) | \( x_0(m,n) \) | \( x_0(m,n+1) \) |
| \( x_0(m+1,n-1) \) | \( x_0(m+1,n) \) | \( x_0(m+1,n+1) \) |

| \( x_0(m-1,n-1) \) | \( x_0(m-1,n) \) | \( x_0(m-1,n+1) \) |
| \( x_0(m-1,n) \) | \( x_0(m,n) \) | \( x_0(m,n+1) \) |
| \( x_0(m+1,n-1) \) | \( x_0(m+1,n) \) | \( x_0(m+1,n+1) \) |

Table 3.1 : Polyphase composition

Where \( x(m,n) \) represents the current location pixel value. \( y_1(m,n), y_2(m,n) \) and \( y_3(m,n) \) are horizontal, vertical and diagonal pixel value respectively. This is obtained by using context formation, as shown in table 3.1. The inputs \( x, y_1, y_2 \) and \( y_3 \) are applied to the Decision Map “D”. Depending on the condition, it selects one update filter and followed by prediction, as shown in figure 3.3.

\[
xx = 0.4 * y + (0.2*yh+0.2*yv+0.2*yd)
\]

In this decomposition, \( xx \) is called the approximation band and \( y_1', y_2', y_3' \) are called the horizontal, the vertical, and the diagonal detail bands, respectively. At every position \( n = (m, n) \), the update step is triggered by the outcome \( d_n = D(x, y_1, y_2, y_3)(n) \), where \( D \) represents the decision map. The output \( d_n \) triggers the specific choice of the update step in the following sense

\[
xx(n) = \alpha_{dn} x(n) + \sum_{j=1}^3 \mu_{dn,j} y_j(n) \quad (3.6)
\]

Where \( \alpha_{dn} \) and \( \mu_{dn} \) are the filter co-efficient. Note that the filter coefficients depend on the decision \( d_n \) which may change depending on the local characteristics of the input signals. We assume that the decision map only depends of the gradient vector \( v(n) \), with components \( v_j(n) \) given by

\[
v_j(n) = x(n) - y_j(n), \quad j = 1, 2, 3. \quad (3.7)
\]

The filter co-efficient in (1), assumed that

\[
\alpha_d + \sum_{j=1}^3 \mu_{d,j} = 1 \quad \text{For } d = 0, 1, N-1, \quad (3.8)
\]

With \( \alpha_d \neq 0 \) for all \( d \).

In this way, we present the way of constructing the decision map by comparing different norms, each of them capturing different orientation features. Let us consider \( N \) norms, denoted by \( P_0, P_1, \ldots, P_{N-1} \), and a decision map which can take \( N \) values, \( d(v) \in \{0, 1, \ldots, N-1\} \).

The decision criterion will be based on the comparison, at each sample, between the values of the norms. In this project considering \( N = 3 \), a possible construction of the decision maps, and hence of the decision regions, and its corresponding filter equations are described on the relations below.

**Decision Region-I**

\[
d = 1 \iff \begin{cases} P_1(v) < P_2(v) \\ P_1(v) \leq P_2(v) \end{cases} \Rightarrow xx = 0.4 * y + (0.2*yh+0.2*yv+0.2*yd)
\]

**Decision Region II**
\[ d = 2 \iff \begin{cases} P_2(v) < P_3(v) \\ P_3(v) < P_1(v) \end{cases} \quad \Rightarrow \quad xx = 0.5 * y + (0.2)^{*}(yh) + (0.15)^{*}yv + (0.15)^{*}yd \]

**Decision Region III**

\[ d = 3 \iff \begin{cases} P_3(v) \leq P_1(v) \\ P_3(v) \leq P_2(v) \end{cases} \quad \Rightarrow \quad xx = 0.45 * y + (0.2)^{*}(yh) + (0.2)^{*}yv + (0.15)^{*}yd \]

**Norms:**

Let \( v(n) \) be the gradient vector with components, \((v_1(n), v_2(n), \ldots, v_N(n)))^T \) (where T represents transposition), then

- L_1 norm is defined as,
  \[ P_1(v) = \sum_{j=1}^{N} |v_j| \]

- L_2 norm is defined as,
  \[ P_2(v) = \left( \sum_{j=1}^{N} v_j^2 \right)^{1/2} \]

In general, the ‘r’th norm is defined as,

\[ P_r(v) = \left( \sum_{j=1}^{N} v_j^r \right)^{1/r} \]

and the \( L^\infty \) norm is defined as, \( P_\infty(v) = \max |v_j|, j = 1, 2, \ldots, N \).

The gradient vector at synthesis side is given by \( v'(n) \) with components

\[ v'_j(n) = xx(n) - y'_j(n), \quad j = 1, 2, \ldots, J. \quad \text{(3.9)} \]

is related to gradient vector at analysis side \( v(n) \) by means of the linear relation \( v'(n) = A_d v(n) \).

Where \( A_d = I - ub_d^T \), \( I \) is the \( J \times J \) identity matrix, and \( u = (1, \ldots, 1)^T \), \( b_d = (\mu_{d,1}, \ldots, \mu_{d,J})^T \) are vector of length \( J \).

The super index ‘T’ denotes transposition. To have Perfect Reconstruction (PR), we must be able to recover the decision \( D_n \) from the gradient vector at synthesis \( v'(n) = A_d v(n) \).

That is, for all \( n \)

\[ D(x, y_1, y_2, y_3)(n) = D(x, y_1, y_2, y_3)(n) \quad \text{(3.10)} \]

Similar to analysis, here also constructed the decision Map, and hence of the decision regions, and its corresponding filter equations are described on the relations below, as well as the necessary and sufficient condition for Perfect Reconstruction (PR) specified,

**Decision Region I**

\[ d = 1 \iff \begin{cases} P_1(A_1 v) < P_3(A_1 v) \\ P_1(A_1 v) \leq P_2(A_1 v) \end{cases} \quad x = (1/0.4)^{*}(ry - (0.2)^{*}xh + 0.2)^{*}xv + 0.2)^{*}xd) \]

**Decision Region II**

\[ d = 2 \iff \begin{cases} P_2(A_2 v) < P_3(A_2 v) \\ P_2(A_2 v) \leq P_1(A_2 v) \end{cases} \quad x = (1/0.5)^{*}(ry - (0.2)^{*}xh + 0.15)^{*}xv + 0.15)^{*}xd) \]

**Decision Region III**

\[ d = 3 \iff \begin{cases} P_3(A_3 v) \leq P_1(A_3 v) \\ P_3(A_3 v) \leq P_2(A_3 v) \end{cases} \quad x(1,1) = (1/0.45)^{*}(ry - (0.2)^{*}xh + 0.2)^{*}xv + 0.15)^{*}xd) \]

This table shows compression ratio analysis with respect to different levels

**Quality Measures of Reconstructed Images:**

For characteristic quality measures of the image traditionally calculated and evaluated by means of :

1) **Mean Square Error (MSE)** and
2) **Peak Signal to Noise Ratio (PSNR)** Ratio.

1) **Mean Square Error (MSE)**:

This is one of the mathematical model known as reconstruction error variance \( \sigma_q^2 \). Which includes the MSE between the original image \( f \) and the reconstructed image \( g \) at decoder is given by the equation:

\[ \text{MSE} = \sigma_q^2 = \frac{1}{N} \sum_{j,k} (f[j,k] - g[j,k])^2 \]

Where, \( j, k \) – Denotes the sum over all pixels in the image and

\( N \) is the number of pixels in each image.

Therefore, it is decided that peak signal-to-noise ratio is nothing but ratio between signal variance and reconstruction error variance.

2) **Peak Signal to Noise Ratio (PSNR)**:

Further statistical model has been derived for the said ratio between two images having 8 bits per pixel is given by:
PSNR = 10 \log_{10} \left( \frac{255^2}{\text{MSE}} \right)

Which, is measured in terms of decibels (dBs).

Study and observations concludes that, when PSNR is 40 dB and more, then the original and the reconstructed images are virtually indistinguishable by human eyes.

Taking into consideration these models various experiment has been carried out and observations are recorded in the table (2.1a & 2.1b), which shows that Bitrate and Decomposition Level comprises the values of PSNR for getting quality value of PSNR measures the various uncertainties i.e. for certain value of Bitrate then exact prediction of decompression level is highly impossible.

Further study and analysis understand that, needs to be improve the methodology to overcome the said problem so that exact Bit Rate (BR) to be decided to obtain the quality image decompression(David Salomon’s) at suitable and sustainable Decomposition Level (DL).

To dilute this sensitive problem and for getting predictable results for image compression it has been decided that use of Fuzzy logic technique which is most suitable and flexible, it is described in the next section.

### Table(2.1a) : Sample Image (256 X 256)

<table>
<thead>
<tr>
<th>Decom Level/ Bitrate</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1</td>
<td>6.1665</td>
<td>8.4572</td>
<td>10.6564</td>
<td>15.2128</td>
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<td>18.9888</td>
<td>17.6994</td>
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<tr>
<td>0.4</td>
<td>8.5532</td>
<td>10.9536</td>
<td>19.1481</td>
<td>18.6787</td>
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<tr>
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<td>12.1762</td>
<td>19.1628</td>
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### Table(2.1b) : Sample Image (256 X 256)

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<th>6</th>
<th>7</th>
<th>8</th>
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### Table(2.2) : Sample Image

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<th>Bit Rate</th>
<th>Most Suitable PSNR</th>
<th>Respective Decomposition Level</th>
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</thead>
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<td>0.3</td>
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</tr>
<tr>
<td>0.4</td>
<td>19.1481</td>
<td>3</td>
</tr>
<tr>
<td>0.5</td>
<td>19.1628</td>
<td>3</td>
</tr>
<tr>
<td>0.6</td>
<td>20.6154</td>
<td>3</td>
</tr>
<tr>
<td>0.7</td>
<td>20.6249</td>
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<tr>
<td>0.8</td>
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</tr>
<tr>
<td>0.1</td>
<td>15.7433</td>
<td>5</td>
</tr>
</tbody>
</table>

1) Steady state characteristics:

2) Fuzzy Input Variable : PNSR

<table>
<thead>
<tr>
<th>Fuzzy Membership Functions for Input variables</th>
<th>Min. Value</th>
<th>Middle Value</th>
<th>Max Value</th>
</tr>
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</table>
In this fuzzy logic optimization technique for decision making gives the result of bitrates is 0.4, which is most suitable for all uncertainties with every decomposition level. Mathematical model used in the wavelet transformation (Ajit S. Bopardikar) has found some limitations and which introduces amount of error in the entire image process results. Image compression based on adaptive and non-adaptive (Haar) wavelet decomposition. This results in the decreases in quality and efficiency of the processed image. Therefore to overcome this sensitive issue, another mathematical less model is embedded for enhancing the present algorithm which is Fuzzy Logic Technique (FLT).

### REFERENCES